

## Arvind Borde / PHY 11, Week 8: Rotational Motion

When we discussed centripetal acceleration, we looked at objects moving in a circle at fixed speed.

We'll study rotational motion from a more general point of view here.

In general, rotational motion is related to linear: the wheels on a car go \_\_\_\_\_ and the car moves forward \_\_\_\_\_.

1

The magnitudes of *kinematical* rotational quantities are related to those of linear ones through multiplication by the radius:

Displacement:  $d = r\theta$

Speed/velocity:  $v = r\omega = r \frac{\Delta\theta}{\Delta t}$

Acceleration:  $a_T = r\alpha = r \frac{\Delta\omega}{\Delta t}$

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In each case the same word is used in the rotational world with a "rotational" or "angular" tagged onto the linear word.

For example:

$\omega$ : "rotational velocity" or "angular velocity."

If a new word is needed, it is explicitly stated.

3

When the equations  $d = r\theta$ ,  $v = r\omega$  hold, where  $v$  is the total linear velocity of an object, we call it "rotation without slipping."

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Radians are unitless (they are ratios of lengths). Thus  $d$  and  $r$  above will have the same units, and, since  $v$  is in m/s (SI),  $\omega$  is in \_\_\_\_\_.

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Conversions (based on  $360^\circ \sim 2\pi$  – full circle):

Degrees to radians:  $[\theta^\circ] \times \frac{\pi}{180^\circ}$

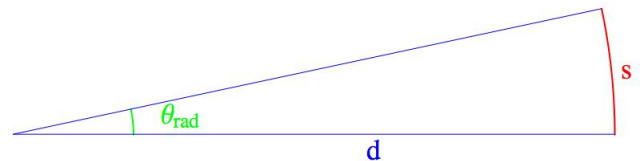
Radians to degrees:  $[\theta_{\text{rad}}] \times \frac{180^\circ}{\pi}$

(1) Convert  $15^\circ$  to radians. \_\_\_\_\_

(2) Convert 15 rad to degrees. \_\_\_\_\_

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There's a relationship between the radian measure of an angle and distance:



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### ADDITIONAL NOTES

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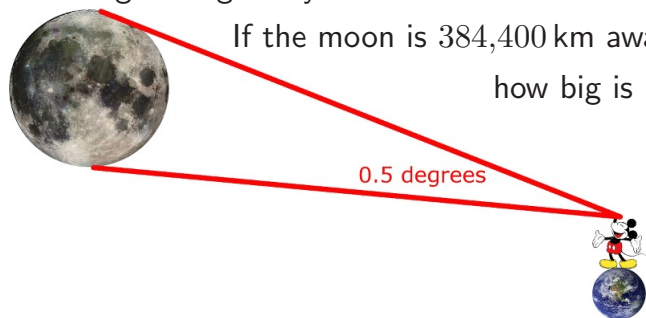
\_\_\_\_\_

\_\_\_\_\_

\_\_\_\_\_

\_\_\_\_\_

(3) You are gazing at the moon. It occupies a half degree angle in your field of view as shown.



If the moon is 384,400 km away, how big is it?

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Assume rotation without slipping below.

(4) If your car has wheels of radius 30 cm, how far does it move over one full rotation of the wheels?

$$d =$$

(5) If your wheels are spinning at 2000 rpm how fast are you traveling?

$$\omega =$$

$$v =$$

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The angular or rotational acceleration is tangent to the direction of motion. This is different from the centripetal acceleration, which is \_\_\_\_\_:

$$a_C = \frac{v^2}{r} = \frac{r^2\omega^2}{r} = \omega^2 r$$

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The \_\_\_\_\_ of rotational motion is

$$f = \frac{\omega}{2\pi}$$

measured in rev/sec, also called Hertz (Hz): 1 Hz equals 1 rev/sec. It follows that  $\omega = 2\pi f$ .

The \_\_\_\_\_ of rotational motion (time for one revolution) is

$$T = \frac{1}{f}$$

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The equations that govern rotational motion under \_\_\_\_\_ mirror their linear counterparts (initial displacement zero):

A] \_\_\_\_\_

B] \_\_\_\_\_

C] \_\_\_\_\_

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(6) Starting from rest, if your car wheels reach an angular speed of 120 rad/s in 1 min, what is the angular acceleration?

Use  $\omega =$  \_\_\_\_\_.

So \_\_\_\_\_,

or  $\alpha =$  \_\_\_\_\_.

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ADDITIONAL NOTES

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The relationship of *dynamical* linear quantities to their rotational counterparts is not always so simple, but here's a list of the two sets:

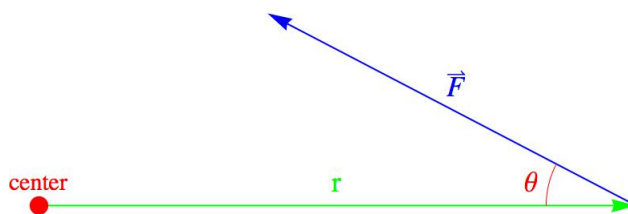
Linear		Rotational	
Inertia:	$m$ ,	Moment of inertia:	$I (= mr^2)$
Force:	$F$ ,	Torque:	$\tau$
Momentum:	$p$ ,	Angular momentum:	$L$

The last two are vectors.

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Torque is the rotational version of force:

$$\tau = rF \sin \theta$$



The greater the torque, the “easier” it is to “make rotation.”

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(7) You push a 120 cm door with a 35 N force perpendicular to it. What's the torque exerted if

(a) you push furthest from the hinge?

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(b) you push at the midpoint?

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(c) you push at the hinge?

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(8) With the numbers in the previous problem what is the torque if push furthest from the hinge, but at an angle (with the door) of

(a) 60°? =====

(b) 1°? =====

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Just as the inertia of a body is a measure of its resistance to force, the moment of inertia of a body is a measure of its resistance to \_\_\_\_\_:

The formula given above,  $I = mr^2$ , is for a point mass a distance  $r$  from the center of rotation.

For a solid object, the distribution of the mass plays an important role.

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Think of an extended object as being made up of many small masses.

Suppose you have two objects of the same shape, size and total mass, but object A has most of its mass concentrated at its center, and object B has most of its mass at its edges.

(9) Which do you expect to have the greatest  $I$ ?

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ADDITIONAL NOTES

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Within the rotational world the relationship of rotational quantities parallels that of linear ones:

$p = mv:$	$L = I\omega$
$F = ma:$	$\tau = I\alpha$
$F = \Delta p/\Delta t:$	$\tau = \Delta L/\Delta t$
$KE = \frac{1}{2}mv^2:$	$KE_{\text{rot}} = \frac{1}{2}I\omega^2$
$W = Fd:$	$W = \tau\theta$
$P = \Delta W/\Delta t:$	$P = \tau\theta/\Delta t = \tau\omega$

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The total KE of a moving object is a sum of linear and rotational:

$$KE_{\text{total}} = \frac{1}{2}mv^2 + \frac{1}{2}I\omega^2$$

As with linear momentum, the angular momentum,  $L = I\omega$ , of an isolated system is conserved.

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(10) What's the  $KE_{\text{rot}}$  of an object with  $I = 3 \times 10^{-3} \text{ kg}\cdot\text{m}^2$  that's spinning at 8000 rpm?

Note: It's common to be given rotational speeds in rpm. You must convert to rad/s.

$\omega =$

$KE_{\text{rot}} =$

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ADDITIONAL NOTES

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